## Digital Tachometer

Standard input series Differential input series
4961X / 4961F

## Instruction Manual



Thank you for purchasing TSURUGA Digital Tachometer 4961X/ 4961F. For instructions on how to use this product properly and optimally for a long period of time, please be sure to read this manual thoroughly before use.

When you purchase the product with optional equipment: Please refer to the operation manual of the optional equipment.

Before operation, maintenance and inspection, please carefully read this instruction manual and follow it for proper use.

After reading, be sure to store this manual in a safe, convenient place where operators can always refer to it easily.

| CAUTION |
| :--- |
| Electric Shock. <br> Be sure to turn the power OFF when wiring as well as <br> inspecting the unit. <br> Failure to do so could result in electric shock. <br> DO NOT block the ventilation holes on the side of the main unit. <br> DO NOT put any foreign objects or materials inside the unit <br> through these holes. <br> Failure to follow this could result in abnormal heat generation <br> and/or malfunctions. |
| DO NOT touch the unit with wet (or sweaty) hands when <br> inspecting or for wiring. <br> Failure to do this could result in electric shock. |


| Power |
| :--- |
| - Be sure to use the unit under the specified voltage (AC power |
| specifications: $85-264 \mathrm{VAC} / \mathrm{DC}$ power specifications: $10.8-25.2 \mathrm{VDC}$ ). |
| - Inverter power source cannot be used. |
| Input signal wire |
| - Connection wiring from sensors shall not be kept in the same or parallel conduit or |
| cable as the power source, power or high voltage cables. If you fail to separate the |
| wiring, noise may be superimposed on the signal wire, resulting in malfunctions. |
| - Use shielded wire for input power connections with the shortest possible metal conduit. |
|  |
| Terminal |
| - Check that the screws have not come loose due to vibrations after a certain period of time. |
| Operating environment |
| - Do not install the unit in the following places or conditions. |
| - Places exposed to direct sunlight, or places where the ambient temperature |
| exceeds a range of 0 - $45^{\circ} \mathrm{C}$. |
| • Places where the relative humidity percentage exceeds a range of 35 - $85 \%$, or |
| places subject to condensation due to rapid change in humidity. |
| • Places subject to corrosive and/or combustible gases. |
| • Places subject to a large amount of dust, salinity, and/or ferric substance. |
| • Places susceptible to noise (including static electricity). |

## Safety Requirements

Be sure to observe

Before operation, maintenance and inspection, please carefully read this instruction manual and follow it for proper use. Please carefully read all information related to this unit and safety, and precautions before use.
This instruction manual categorizes safety precautions as "DANGER", "WARNING", and "CAUTION". Each of them is an important description related to safety. Be sure to observe.


Improper use by neglecting the following precautions may result in the potential for fire, serious injuries, and/or death.


WARNING
Improper use may result in serious injuries.


CAUTION
Improper use may result in minor injuries or property damage.
-Limited Warranty

- We are not responsible for damages resulting from negligence through failure to follow the instructions set out in this manual.
- We are not responsible for damages resulting from earthquake and/or fire unrelated to us, actions by third parties, or any other accidents, intentional or through customer negligence, as well as from accidents caused by misuse or improper use under abnormal conditions.
- For information regarding assurance provisions, please read the attached warranty certificate.


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## 1. Installation to the Start of Operation

This unit is designed for use according to your measurement purposes.
Before use, follow the procedures below from installation to the start of operation.

## Check before use


(1) Installation of waterproof gasket
(2) Fixation to the panel

Function (action configuration) p. 8 settings
(1) Press and hold the SHIFT + FUNC keys for 5 seconds or more and start setting.
(2) Press the $\boldsymbol{\Delta}$ key to select the item, and press the ENT key to start changing the setting value.
(3) Press the key to move to another digit, and after changing the value using the - key, use the ENT key to finish the setting value change.
(4) After setting all functions, use the SET key to finish setting.

| Memory function <br> settings | p.17-19 |
| :--- | :--- |

(1) Press the MEM key once to display the MAX value.
(2) Press the MEM key again to display the MIN value.
(3) Press the MEM key once again to display the normal measurement value.
*You can use the unit without setting various functions.
 $\square$

| Connection with the <br> power and sensor | p.5-6 |
| :--- | :--- |



1) Connection with the power
2) Connection with various sensors

路 | Parameter settings | p.8-15 |
| :--- | :--- |

Mode (function) settings $\mathrm{p} .8-15$

1) Press and hold the SHIFT +

PAR keys for 5 seconds or more and start setting.
(2) Press the $\boldsymbol{\Delta}$ key to select the item, and press the ENT key to start changing the setting value.
(3) Press the $\square$ key to move to another digit, and after changing the value using the $\triangle$ key, use the ENT key to finish the setting value change
(3) After setting all parameters, use the SET key to finish setting

MOD keys and start setting
(2) Use the $\boldsymbol{\Delta}$ key to set, and use the SET key to finish setting.

## 2. Unit Model

Please check the model number of the equipment purchased.
$\urcorner$ 4961X


| Symbol | Output | Function |
| :---: | :--- | :--- |
| FVT | Analog Signal Output | Outputs voltage and current that correspond to displayed value |
| CPT | Relay Output | Relay Changeover contact output. H output, L output, and GO <br> output, against the set value |
| TRT | Transistor Output | Open Collector Output. HH, H, LL, L GO and ZERO output. |

Power

| Symbol | Input type |
| :---: | :--- |
| 4961 X | Standard input : Supports the sensor input, including rotary encoders, and magnetic sensors |
| 4961 F | Differential input Supports the line driver output, including AC servo motors |



## 3．Specifications

| Unit model |  | 4961X／4961F |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Display | Action mode | Digital tachometer mode | Flowmeter mode | Elapsed timecounter mode | Time width meter mode |
|  | Display 1 | $\begin{gathered} 0-999999 \\ 6 \text { digits } \end{gathered}$ |  | 0：00：00－9：59：59 （Hour：Minute：Second／base 60 display） | 0：00：00－0：59：59 （Hour：Minute：Second／base 60 display） |
|  | Display 2 |  |  | 0：00－999：99（Hour：Minute：Second／base 10 display） |  |
|  |  | With zero suppression function |  |  |  |
| Decimal point position |  | 0 to 5 digits after the decimal point（ $000000 \sim 0.00000$ ） |  | －－ |  |
|  | er indicator | Red 7 segment LED，Letter height 22 mm ， 6 digits，－display available |  |  |  |
|  | D lamp | 8 （SIG，LL，L，H，HH，MAX，MIN，TEA） |  |  |  |
|  | ration key | 5 （SET／SHIFT ，MEM／TEACH， $\boldsymbol{\triangle} /$ PARA，／FUNC ，ENT／MODE） |  |  |  |
|  | ut range | $0.0067 \mathrm{~Hz} \sim 100 \mathrm{kHz}$ |  |  | 10ms－ 3600 s |
| Measu | ment accuracy | $\pm 0.008 \% \pm 1$ digit |  |  | $\pm 0.1 \% \pm 1$ digit |
|  | Filter | Switches between $100 \mathrm{kHz}, 30 \mathrm{kHz}, 10 \mathrm{kHz}$ ，and 0.02 kHz using the parameter． <br> Note that you can switch between only 10 kHz and 0.02 kHz in a magnetic sensor，and its contact is only 0.02 kHz ． |  |  |  |
|  | play cycle | $0.2,0.5,1,2,5,10,15,30,60 \mathrm{sec}$ ．（changeable in the parameter settings） |  |  | Dependent on the input signal |
|  | ale function | Parameter setting system using the front panel keys．The teaching（combination）of display values are also available． |  |  |  |
|  | ry function | The maximum／minimum measurement values can be memorized and displayed in the indicator． （Switches the display using the MEM key） |  |  |  |
| Com | tor function | The settings of the high set point 1，low set point 1，high set point 2，and low set point 2，and judgment results can be displayed on the LED lamp．The hysteresis setting of the high and low set point 1 values are also available． |  |  |  |
|  | zero time | $0.1-150 \mathrm{sec}$ ． |  | 0．1－3600 sec． |  |
| Pre－ar | metic function | Updates the displayed value according to the elapsed time after the pulse stops． |  |  |  |
|  | ng function | Performs scaling automatically by setting the display value with a certain signal input．（only in the tachometer and flowmeter modes） |  |  |  |
| Insu | on resistance | $10 \mathrm{M} \Omega$ or more（at DC500V Mega） |  |  |  |
|  | age proof | AC1500V or more 1min |  |  |  |
| Opera | $g$ temperature | $0-45^{\circ} \mathrm{C}$（No condensation） |  |  |  |
| Ope | ng humidity | 35－85\％RH（No condensation） |  |  |  |
| Oper | g atmosphere | No corrosive gas |  |  |  |
| Conf | ing standard | RoHS |  |  |  |
| Pro | ion function | Front panel：IP66（or equivalent），Rear terminal block：IP20 |  |  |  |
|  | g material | ABS resin |  |  |  |
| Exte | dimensions | W $96 \times \mathrm{H} 48 \times \mathrm{D} 92 \mathrm{~mm}$（DIN） |  |  |  |
| Weight |  | Approx．200g <br> FVT，FVC，TRT，BDC options ：＋approx． 50 g CPT options ：＋approx． 100 g |  |  |  |

＊There are the input specifications in addition to the above specifications．For details，refer to p．5－6．

## 4．Component Part Names and Functions

－Front

－Rear


| № | Name | Function |
| :---: | :---: | :---: |
| （1） | SIG lamp | Lights up when the sensor signal is input |
| （2） | LL lamp | Lights up when the low set point 2 is judged． |
| （3） | L lamp | Lights up when the low set point 1 is judged． |
| （4） | H lamp | Lights up when the high set point 1 is judged． |
| （5） | HH lamp | Lights up when the high set point 2 is judged． |
| （6） | MAX amp | Lights up when the maximum value is displayed |
| （7） | MIN lamp | Lights up when the minimum value is displayed |
| （8） | TEA lamp | Lights up when the teaching function is set |
| （9） | PEAK lamp | Not used |
| （10） | BTM lamp | Not used |
| （11） | Unit label space | Space for attaching the supplied unit labels |
| （12） | Main display | Displays the measurement value |
| （13） | SET／SHIFT key | Finishes the setting in various setting modes Pressing this key with other keys switches to various setting modes |
| （14） | MEM／TEACH key | Switches to the memory display <br> Pressing this key with the SET key goes to the teaching setting mode |
| （15） |  |  |
| （UP）／PARA key | Changes the selected items in various setting modes，or numerical values Pressing this key with the SET key switches to the parameter setting mode |  |
| （16） | －（NEXT）／FUNC key | Changes the selected digit in various setting modes Pressing this key with the SET key switches to the function setting mode |
| （17） | ENT／MODE key | Selects the changed item（s）in various setting modes <br> Pressing this key with the SET key switches to the mode setting mode |
| （18） | Terminal block |  |
| （19） | Rear panel |  |
| （20） | Terminal block cover |  |
| （21） | Mounting adapter |  |

－Side


Unit label

| 分 | PS | ${ }^{\ell} \mathrm{h}$ | $\mathrm{cm}_{\mathrm{min}}$ | $\mathrm{m}_{\mathrm{h}}^{3}$ | 分 | PS | $\ell_{\mathrm{h}}$ | cm min | $\mathrm{m}_{\mathrm{h}}^{3}$ | FVT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 秒 | ${ }^{\circ} \mathrm{C}$ | kHz | rpm | $\ell_{\min }$ | 秒 | ${ }^{\circ} \mathrm{C}$ | kHz | rpm | $\ell$ min | TRT |
|  |  |  |  |  |  |  |  |  |  | FVC |
| 時：分：秒 | sec | min | rps | Hz | h：m：s | sec | min | rps | Hz | TRC |
|  |  |  |  |  |  |  |  |  |  | BCD |
| 分: 秒: 秒\| | m h | $\mathrm{mm}_{\mathrm{s}}$ | $\ell$ | ${ }^{r} \min$ | $\mathrm{m}: \mathrm{s} \text { 秒\| }$ | $\mathrm{m}^{\mathrm{h}}$ | $\underset{\mathrm{s}}{\mathrm{~mm}}$ | $\begin{aligned} & \ell \\ & s \end{aligned}$ | $r^{\min }$ | RMT |
|  |  |  |  |  |  |  |  |  |  | DRT |
|  | \％ | $\mathrm{m}_{\text {min }}$ | $\mathrm{km}_{\mathrm{h}}$ | $\mathrm{mm}_{\mathrm{min}}$ |  | \％ | $m_{\text {min }}$ | $\mathrm{km}_{\mathrm{h}}$ | $\underset{\min }{\mathrm{mm}}$ | SDT |
|  |  |  |  |  |  |  |  |  |  | SDC |

5. External Dimensions



## 6. Installation to the Panel

Mount this unit to the panel according to the following procedures.
Check that the mounting panel is thick enough ( $1.0-5 \mathrm{~mm}$ ) before mounting operation.
1 Attach the provided waterproof gasket to the panel surface.

* If waterproofing is not necessary, skip this step.
(1) Remove the external frame with the cutting lines(backing paper + waterproof gasket) from the gasket sheet.
(Adhesive paste is applied on the both sides of the waterproof gasket.)



## $\triangle$ caution

About waterproofing

- Front panel: IP66 (or equivalent)
- Rear terminal block: IP20 (non-waterproof) Do not install the unit in the following places or conditions.
(1) Places regularly subject directly to water
(2) Places subject to oil splashes and/or medical supplies
(3) Places subject to water splashes on the rear or side face(s).
* The front panel is IP66 (or equivalent) waterproofed, but if water is splashed on the unit, be sure to wipe it off the unit as soon as possible.

3 Attach the mounting adapter to the unit. Slide the mounting adapter until it lightly touches the panel surface.


## 7. Wiring to Power Source and Sensors (4961XA/4961XD)

Note)
In order to prevent electric shock, be sure to turn the power OFF. Be sure to use the unit under the rated voltage (AC power specifications: $85-264 \mathrm{VAC} / \mathrm{DC}$ power specifications: $10.8-25.2 \mathrm{VDC}$ ). The inverter output (output to connect a motor) cannot be used as power. Connection wiring from sensors shall not be kept in the same or parallel conduit or cable as the power source, power or high voltage cables. If you fail to separate the wiring, noise may be superimposed on the signal wire, resulting in malfunctions. Use shielded wire for input power connections with the shortest possible metal conduit.

## For 4961XA/4961XD

-Terminal block connection diagram


* Model

AC power specifications: 4961XA
DC power specifications: 4961XD

- Input specifications

| Item | Description |  |  |
| :---: | :---: | :---: | :---: |
| Power | AC (4961XA) | $85-264 \mathrm{VAC}(50 / 60 \mathrm{~Hz})$ |  |
|  | DC (4961XD) | 10.8-25.2VDC |  |
| Consumption power | 10VA |  |  |
| Sensor power output | DC+12V Max. 100 mA |  |  |
| Open collector input | Open collector (NPN) input |  |  |
|  | LO input | Load capacity 12 mA or more |  |
|  |  | 0-3V |  |
|  | HI input | Leakage current 0.5 mA or less |  |
|  | Maximum frequency 100 kHz (Minimum pulse width 5micro second) |  |  |
| Contact input | For no-voltage contact. Short-circuit (5) and (6) to use. |  |  |
|  | Contact capacity | Voltage 12V, Cu | nt 15 mA or more |
|  | Maximum frequency | 20 Hz (Minimum pu | width 25 micro second) |
| Voltage input | LO input | 0-1.5V |  |
|  | HI input | 4.0-30V |  |
|  | Input resistance | $10 \mathrm{k} \Omega$ |  |
|  | Maximum frequency | 30 kHz (Minimum pulse width 17 micro second) |  |
| Magnetic sensor input | Input resistance | $10 \mathrm{k} \Omega$ |  |
|  | Input voltage | $1 \mathrm{~Hz} \sim 100 \mathrm{~Hz}$ | 0.3 ~ 30Vp-p |
|  |  | $\sim 1 \mathrm{kHz}$ | $1.5 \sim 30 \mathrm{Vp}-\mathrm{p}$ |
|  |  | $\sim 10 \mathrm{kHz}$ | $6 \sim 30 \mathrm{Vp}-\mathrm{p}$ |
|  | Maximum frequency | 10 kHz (Minimum pulse width 50 micro second) |  |

Note) Magnetic sensors cannot be used in the time wide meter mode (mode 3).

- Input circuit

Open collector sensor


## 8. Wiring to Power Source and Sensors (4961FA)

## Note)

In order to prevent electric shock, be sure to turn the power OFF. Be sure to use the unit under the rated voltage (AC power specifications: $85-264 \mathrm{VAC}$ ). The inverter output (output to connect a motor) cannot be used as power. Connection wiring from sensors shall not be kept in the same or parallel conduit or cable as the power source, power or high voltage cables. If you fail to separate the wiring, noise may be superimposed on the signal wire, resulting in malfunctions. Use shielded wire for input power connections with the shortest possible metal conduit.

For 4961FA
-Terminal block connection diagram

-Terminal block connection diagram

| Item | Description |  |
| :---: | :---: | :---: |
| Power | AC (4961FA) | $85-264 \mathrm{VAC}(50 / 60 \mathrm{~Hz})$ |
| Consumption power | 10VA |  |
| Sensor power output | DC+12V Max. 100 mA |  |
| Differential input | Connection to | Differential line driver AM26LS31 etc. |
|  | Differential input voltage |  |
|  |  | Maximum voltage $\pm 5.5 \mathrm{~V}(15 \mathrm{~mA})$ |
|  |  | $\checkmark$ VIF ${ }^{\text {a }}$ Minimum voltage $\pm 3.0 \mathrm{~V}$ |
|  | Maximum frequency | 100 kHz (Minimum pulse width 5 micro second) |

© Wiring requirements

- Use M3 crimp-style terminals with a width of 7 mm or less to connect wires to the terminal block.
- After wire connection to the terminal block is completed, be sure to attach the provided terminal block cover.


## CAUTION

Be sure to connect the power wires to the 1st and 2nd terminals. Incorrect connection could result in damage and/or burns to the unit.
-Line driver input circuit


## 9. Basic Setting Procedure

Conduct settings as indicated below based on the intended use.


Conduct the comparator function $\Rightarrow$ p. 17 and memory function settings $\Rightarrow$ p.18, if necessary.
This unit requires no complicated calculation, and implements the teaching function which enables optional changes of display values and error compensation. (excluding the elapsed timecounter and time wide meter modes)

## 10. Keys to be Used for Various Settings and Their Applications

The front panel keys to be used for mode, parameter, and function settings, as well as various settings (teaching function / high and low set point 1 value setting / memory function) are described below.

- Operation during the normal measurement display / memory display


| № | Name | Function |
| :---: | :---: | :---: |
| (1) | SHIFT key | ng this key with other keys switches to various setting modes |
| (2) | MEM key Switc | Switches to the memory display |
|  | TEACH key Pressi | Pressing and holding this key with the SHIFT key for 5 seconds switches to the teaching setting mode |
| (3) | PARA key Pressi | Pressing and holding this key with the SHIFT key for 5 seconds switches to the parameter setting mode |
| (4) | FUNC key Pressi | Pressing and holding with the SHIFT key for 5 seconds switches to the function setting mode |
| (5) | MODE key Pressi | Pressing and holding this key with the SHIFT key for 5 seconds switches to the parameter setting mode |
| $\bullet$ Operation in the various setting modes |  |  |
| № | Name | Function |
| (1) | SET key | Setting completion key in various setting modes |
| (2) | ( (UP) key | Changes the selected items in various setting modes, or numerical values |
| (3) | - (NEXT) key | Changes the selected digit in various setting modes |
| (4) | ENT key | Selects the changed item in various setting modes |

## 11.Teaching Function Settings

When you can check (measure) the actual revolution speed, the following simple method (teaching function) can be used. The teaching function requires no complicated calculation.

- The teaching function is supported only in mode 1 and mode 4 . Mode 2 and mode 3 have no teaching function.


## ■ Setting method



Teaching function setting mode


When you press the SHIFT + MEM keys simultaneously during the normal measurement display, the main display blinks. (TEA lamp lights up)

The measurement value which was displayed before is displayed in the main display. In the initial status, the digit on the left blinks. Because the value in the blinking digit can be changed, use the key to select the digit in which you want to change the value.
Every time you press the $\square$ key, the digit blinks in the order of "1st digit", "2nd digit", ... "6th digit", and "decimal point", then back to "1st digit".

After selecting the digit you want to change, use the $\boldsymbol{\Delta}$ key to change the value (0-9). When you select the decimal point, use the $\boldsymbol{\Delta}$ key to change the decimal point position.

Returns to the normal measurement display

$$
\begin{array}{|l:l:l:l}
\hline 0 & 1 & 0 & 0
\end{array}: 0
$$

Teaching function details

- Mode 1

The teaching function can be used to automatically change the value of parameter items (P2, P3), and calculate the present measurement value from the teaching setting value as below.

| During normal display |  |  |
| :--- | :--- | :---: |
| External input pulse (Hz) | A |  |
| Parameter setting <br> value | P1 Pulse count per revolution | B |
| P2 Setting revolution speed <br> (detection section) | C |  |
| Display calculation <br> formula | $\{$ Value to be displayed | D |


| When the teaching function is executed |  |  |
| :--- | :--- | :---: |
| Input pulse (Hz) in the teaching setting | A |  |
| Teaching function setting value | F |  |
| Parameter setting <br> value | P1 Pulse count per revolution <br> P2 Setting revolution speed <br> (detection section) | $\mathrm{C}=\mathrm{A} * 60(\mathrm{~Hz}) / \mathrm{B}$ |
|  | P3 Value to be displayed | $\mathrm{D}=\mathrm{F}$ |
| Display calculation <br> formula | $\{(\mathrm{A} / \mathrm{B}) * 60\} *(\mathrm{D} / \mathrm{C})$ |  |

When the input revolution speed is outside the input revolution speed range, "EE-2" is displayed, and the teaching function cannot be used.

> Input revolution speed range : 1rpm $\leqq$ Input revolution speed* $<99999 \mathrm{rpm}$
> *Input revolution speed $=A \times 60(\mathrm{~Hz}) /$ B

* The P2 calculation value is maintained by rounding off fractions after the decimal point.

Depending on input and teaching setting values, the teaching setting value for the input at the time might not be displayed.

## - Mode 4

The teaching function can be used to automatically change the value of parameter items (P3, P4), and calculate the present measurement value from the teaching setting value as below.

| Mode 4 Display value calculation |  |  |  |
| :--- | :--- | :--- | :---: |
| External input pulse (Hz) <br> Parameter setting <br> value | P1 | Number of blades per <br> revolution | B |
|  | P2 | Capacity per sensor blade | C |
|  | P 3 | Scaling | D |
|  | P 4 | Decimal point display | E |
| Display calculation <br> formula | $(\mathrm{A} * \mathrm{~B}) * \mathrm{C} * \mathrm{D}$ |  |  |


| Mode 4 Display value calculation |  |  |  |
| :---: | :---: | :---: | :---: |
| Input pulse (Hz) in the teaching setting |  |  | A |
| Teaching function setting value |  |  | F |
| Parameter setting value | P1 | Number of blade per revolution | B |
|  |  | Capacity per sensor blade | C |
|  |  | Scaling | $\mathrm{D}=\mathrm{F} /(\mathrm{A} * \mathrm{~B} * \mathrm{C})$ |
|  |  | Decimal point display | Decimal point position of $\mathrm{E}=\mathrm{F}$ |
| Display calculation formula | $(\mathrm{A} * \mathrm{~B}) * \mathrm{C} * \mathrm{D}$ |  |  |

When the input frequency is outside the input frequency range, "EE-2" is displayed, and the teaching function cannot be used.

## Input frequency range : 1Hz $\leqq \mathrm{A}<99999 \mathrm{~Hz}$

* The P3 scaling value maintains values after decimal point up to 7 digits inside. Note that because the number of digits after decimal point that can be maintained in the parameter setting is up to 5 , values in 5 digits or more after decimal point will be rounded off when you enter the value in the parameter setting.
* If the P3 calculation value exceeds 999999, the P3 value will be forced to be "999999".

12. About Mode

4961X / 4961F have five modes (functions) which can be selected according to the measurement purpose.

| Mode <br> No. | Mode description |  | Details | Page No. <br> for the setting method |
| :---: | :--- | :--- | :---: | :---: |
| 1 | Digital Tachometer Mode* | Digital tachometer / used as speedmeter Displays the proportional value to the input | p.8-9 |  |
| 2 | Elapsed Timecounter Mode | Used as the elapsed time display in a certain period Displays the inversely proportional value to the input | p.10-11 |  |
| 3 | Time Width Meter Mode | Measures time for the period when the signal is ON (or OFF) and displays it | p.12-13 |  |
| 4 | Flowmeter Mode | Displays the instantaneous flow amount | p. $14-15$ |  |
| 99 | Test Mode | Executes the self diagnosis | p. 19 |  |

* The mode 1 (digital tachometer mode) is set in the factory setting.

For the lists of parameters and functions to be set in each mode, refer to pages 20 and 21.

## 13. Setting Method When You Select Mode 1 (Digital Tachometer Mode) for Measurement Digital tachometer mode

Set each setting item for mode and parameter according to the following procedures.
(For the setting method of functions, refer to pages 16 and 17.)
■ Setting example (for measuring the peripheral speed of the roller)


As in the figure on the left, the rotary encoder is connected to the feed roller via coupling in the paper manufacturing process. To display the peripheral speed ( $\mathrm{m} / \mathrm{min}$.) of the feed roller in $4961 \square$ under the following conditions:
[Conditions]

- Servo motor (pulse input)
- Diameter of the feed roller
- Peripheral speed of the roller diameter of 90 mm : $(0.09 \mathrm{~m} \times 3.14) \times 500 \mathrm{rpm}=141.3 \mathrm{~m} / \mathrm{min}$
$\stackrel{\text { Circumference }}{\stackrel{0}{4}} \underbrace{L}_{\text {Revolution }}$
of the roller speed*
*Suppose that the revolution speed in the detection section is 500 rpm because the revolution speed is not instructed.


## ■ Setting method

(1) Mode

- When you select mode 1 (digital tachometer mode) for measurement (The digital tachometer mode is set in the factory setting.)


Note) If you change the mode settings, each parameter and function setting value will return to the factory default setting value.
(2) Parameter

- Parameter setting items in mode 1 (digital tachometer mode) nd numerical values to be set according to the above example

| No. | Setting item | Setting range | Default setting value |  | Numerical value to be set according to the above example |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Display | Description |  |  |
| P1 | Pulse count per revolution | $1-9999 \mathrm{p} / \mathrm{r}$ | _ _ 0001 | $1 \mathrm{p} / \mathrm{r}$ | 600p/r | Enter the pulse count of the rotary encoder. |
| P2 | Revolution speed in the detection section | 1 - 99999 rpm | _01000 | 1000 rpm | 500 rpm | Enter some numerical value as the revolution speed is not instructed. |
| P3 | Value to be displayed (with decimal point) | 0.00001-999999 | 001000 | 1000 | 141.3 | Refer to the above "Setting example". |
| P4 | Display cycle | $\begin{aligned} & \text { 0.2/0.5/1.0/2.0/ } \\ & 5.0 / 10 / 15 / 30 / 60 \mathrm{sec} \\ & \hline \end{aligned}$ | _ 1.0 _ | 1 sec. | 1 sec. | Measure using the default setting value as no special instruction is provided. |
| P5 | Auto zero time | 0.1-150 sec. | - - 006.0 | 6.0 sec . | 6 sec . | Measure using the default setting value as no special instruction is provided. |
| P6 | Input filter | $10 / 30 / 100 / 0.02 \mathrm{kHz}$ | _ 10_ | 10 kHz | 30 kHz | As the rotary encoder is used as a sensor, select " 30 ". |

* For the description about the parameter functions, refer to page 20.
- Mode 1 (digital tachometer mode) Display value calculation equation

- Start setting according to the setting example on the previous page.

*If you enter a value outside the setting range, all the input values will blink, which indicates the setting is disabled.
When this occurs, you cannot switch to other displays until you enter a value within the setting range.
(3) Function (For the setting method, refer to pages 16 and 17.)
$\bullet$ Function setting item in mode 1 (digital tachometer mode)

| No. | Setting item | Setting range | Input range | Default value |
| :---: | :--- | :--- | :---: | :---: |
| F1 | High set point 1 value | Sets the high set point 1 value | $000000-999999$ |  |
| F2 | Low set point 1 value | Sets the high set point 1 value | $000000-999999$ |  |
| F3 | High set point 2 value | Sets the high set point 2 value | $000000-999999$ |  |
| F4 | Low set point 2 value | Sets the low set point 2 value | $000000-999999$ |  |
| F5 | Hysteresis of the high and <br> low set point 1 values | Sets the hysteresis of the high and low set point 1 <br> values | $0-99$ | 0 |
| F6 | Judgment output timer at <br> startup | Sets the time when the comparator judgment is output <br> at startup | $0-99$ sec. |  |
| F7 | Minimum revolution speed | Sets the revolution speed to be displayed as zero | 0 |  |
| F8 | Frequency of the moving <br> average | Used when variation of the revolution speed is large <br> and a stable display cannot be attained | 0 (disabled)/1(3 times)/2(10 times) | $0(d i s a b l e d)$ |
| F9 | Pre-arithmetic function | Promptly performs the deceleration display when the <br> signal is lost | 0 (disabled)/1(enabled) | $0(d i s a b l e d)$ |

[^0]Set each setting item for mode and parameter according to the following procedures.
(For the setting method of functions, refer to pages 16 and 17.)

- Setting example (for the elapsed time display of oven)


As in the figure on the left, bread passes through the oven in a bread factory. The rotary encoder is attached to the motor of the conveyor belt. To display the time at which the bread passes through the oven in 4961ם, do so under the following conditions:
[Conditions]

- Revolution speed of the rotary encoder :

1200rpm(rotary encoder 60p/r)

- Speed of the conveyor belt : $2.8 \mathrm{~m} / \mathrm{min}$
- Length of the oven : 5m
- Passing time through the oven :
$5 \mathrm{~m} \div 2.8 \mathrm{~m} / \mathrm{min}=1.786$ minutes $\rightarrow$ Approx. 1 minute 47 seconds


## - Setting method

(1) Mode

- Set the mode 2 (elapsed timecounter mode).


Note) If you change the mode settings, each parameter, function, and high and low set point 1 setting value will return to the factory default setting value.
(2) Parameter

- Parameter setting items in mode 2 (elapsed timecounter mode) and numerical values to be set according to the above example.

| No. | Setting item |  | Setting range | Default setting value |  | Numerical value to be set according to the above example |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Display | Description |  |  |
| P1 | Pulse count per revolution |  |  | $1-9999 \mathrm{p} / \mathrm{r}$ | __0001 | $1 \mathrm{p} / \mathrm{r}$ | 60p/r | Enter the pulse count of the rotary encoder. |
| P2 | Revolution speed in the detection section |  | 1000-99999rpm | _01000 | 1000rpm | 1200rpm | Enter the revolution speed of the rotary encoder. |
| P3 | Value to be displayed | Hour:Minute:Second display system Second display system | 0:00:01-9:59:59 | _010:00 | 10:00 sec. | Hour:Minute:Second display system 0:01:47 | Refer to the above "Setting example". |
| P4 | Display cycle |  | $\begin{aligned} & 0.2 / 0.5 / 1.0 / 2.0 / \\ & 5.0 / 10 / 15 / 30 / 60 \mathrm{sec} . \end{aligned}$ | _ 1.0 _ | 1 sec . | 1 sec . | Measure using the default setting value as no special instruction is provided. |
| P5 | Auto zero time |  | 0.1-150 sec. | _ - 006.0 | 6.0 sec . | 6 sec . | Measure using the default setting value as no special instruction is provided. |
| P6 | Input filter |  | 10/30/100/0.02kHz | _ 10_ | 10 kHz | 30 kHz | As the rotary encoder is used as a sensor, select "30". |

* For the description about the parameter functions, refer to page 20.

Mode 2 (elapsed timecounter mode) Display value calculation equation


- Start setting according to the setting example on the previous page.

*If you enter a value outside the setting range, all the input values will blink, which indicates the setting is disabled.
When this occurs, you cannot switch to other displays until you enter a value within the setting range.
(3) Function (For the setting method, refer to pages 16 and 17.)
-Function setting item in mode 2 (elapsed timecounter mode)

| No. | Setting item | Description | Input range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| F1 | High set point 1 value | Sets the high set point 1 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system$0: 00$ |
|  |  | Sets the high set point 1 value (Second display system) | 0:00-999:99 |  |
| F2 | Low set point 1 value | Sets the low set point 1 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display0:00 |
|  |  | Sets the low set point 1 value (Second display system) | 0:00-999:99 |  |
| F3 | High set point 2 value | Sets the high set point 2 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display$0: 00$ |
|  |  | Sets the high set point 2 value (Second display system) | 0:00-999:99 |  |
| F4 | Low set point 2 value | Sets the low set point 2 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display$0: 00$ |
|  |  | Sets the low set point 2 value (Second display system) | 0:00-999:99 |  |
| F5 | Hysteresis of the high and low set point 1 values | Sets the hysteresis of the high and low set point 1 values | 0-99 | 0 |
| F6 | Judgment output timer at startup | Sets the time when the comparator judgment is output at startup | 0-99 sec. | 0 sec . |
| F7 | Minimum revolution speed | Sets the revolution speed to be displayed as zero | 000000-999999 | 0 |
| F8 | Frequency of the moving average | Used when variation of the revolution speed is large and a stable display cannot be attained | 0(disabled)/1(3 times)/2(10 times) | 0(disabled) |
| F9 | Pre-arithmetic function | Promptly performs the deceleration display when the signal is lost | 0(disabled)/1(enabled) | 0(disabled) |

* For the description of functions, refer to page 21.

Note) When the input signal stops in the elapsed timecounter mode, the display will overflow after the specified time set with the auto zero function.
The overflow display "......." does not mean there is a malfunction. When the input signal is within the display range, the display returns to normal.
15. Setting Method When You Select Mode 3 (Time Width Meter Mode) for Measurement

Set each setting item for mode and parameter according to the following procedures.
(For the setting method of functions, refer to pages 16 and 17.)
Setting example (for the operating time display of the press machine)


As in the figure on the left, when the press machine finishes operation and returns to the upper edge, the adjacent switch is activated. To display the operating time of the press machine (when the proximity switch is turned off)

- Setting method
(1) Mode
-Set mode 3 (Time Width Meter Mode).


Note) If you change the mode settings, each parameter, function, and high and low set point 1 setting value will return to the factory default setting value.
(2) Parameter

- Parameter setting items in mode 3 (Time Width Meter Mode) and numerical values to be set according to the above example.

| No. | Setting item | Setting range | Default setting value |  | Numerical value to be set according to the above example |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Display | Description |  |  |
| P1 | Switch between Hour:Minute: Second and 1/100 Second system | 0:00:00/0:00 | 0:00 | 1/100 sec. | 0:00 | Select the $1 / 100$ second display based on the operating time of the press machine. |
| P2 | Measurement section | 0(OFF)/1(ON) | 1 | ON | 0 | Select "0" because the adjacent switch of the open collector is OFF. |
| P3 | Auto zero time | $0.1-3600 \mathrm{sec}$. | _3600.0 | 3600 sec . | 60.0 sec . | Set "60.0" because there is no time setting longer than 1 minute. |
| P4 | Input filter | $10 / 0.02 \mathrm{kHz}$ | _ 10_ | 10 kHz | 10 kHz | Measure using the default setting value as no special instruction is provided. |

* For the description about the parameter functions, refer to page 20.
© About the measurement section (parameter 2)

- Start setting according to the setting example on the previous page.

*If you enter a value outside the setting range, all the input values will blink, which indicates the setting is disabled.
When this occurs, you cannot switch to other displays until you enter a value within the setting range.
(3) Function (For the setting method, refer to pages 16 and 17.)

Function setting item in mode 3 (Time Width Meter Mode)

| No. | Setting item | Description | Input range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| F1 | High set point 1 value | Sets the high set point 1 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system 0:00 |
|  |  | Sets the high set point 1 value (Second display system) | 0:00-999:99 |  |
| F2 | Low set point 1 value | Sets the low set point 1 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system 0:00 |
|  |  | Sets the low set point 1 value (Second display system) | 0:00-999:99 |  |
| F3 | High set point 2 value | Sets the high set point 2 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system 0:00 |
|  |  | Sets the high set point 2 value (Second display system) | 0:00-999:99 |  |
| F4 | Low set point 2 value | Sets the low set point 2 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system 0:00 |
|  |  | Sets the low set point 2 value (Second display system) | 0:00-999:99 |  |
| F5 | Hysteresis of the high and low set point 1 values | Sets the hysteresis of the high and low set point 1 values | 0-99 | 0 |
| F6 | Judgment output timer at startup | Sets the time when the comparator judgment is output at startup | 0-99 sec. | 0 sec . |

[^1]Set each setting item for mode and parameter according to the following procedures.
(For the setting method of functions, refer to pages 16 and 17.)
Setting example (For the flow display from the tank)


To display the flow ( $\ell / \mathrm{min}$ ) in $4961 \square$ under the following conditions. when the flowmeter for which the number of blades is unknown as in the figure on the left:
[Conditions]

- Number of blades : Unknown
- Output of the flow sensor : $2.5 \mathrm{cc} / \mathrm{p}$ *p : Pulse
- Setting method
(1) Mode
- Set mode 4 (flowmeter mode).


Note) If you change the mode settings, each parameter, function, and high and low set point 1 setting value will return to the factory default setting value.
(2) Parameter

- Parameter setting items in mode 4 (flowmeter mode) and numerical values to be set according to the above example.

| No. | Setting item | Setting range | Default setting value |  | Numerical value to be set according to the above example |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Display | Description |  |  |
| P1 | Number of blades per revolution | 1-99 | 01 | 1 | 1 | Enter the number of blades of the flowmeter. If it is unknown, enter "1". |
| P2 | Capacity per sensor blade (cc, $\ell$, etc.) | 0.0001-99999 | 0001.0 | 1.0 | $2.5 \mathrm{cc} / \mathrm{p}$ | Enter the capacity per blade that the sensor can read. |
| P3 | Scaling | 0.00000-999999 | 00001.0 | 1 | 0.06 | Refer to "About scaling" below. |
| P4 | Decimal point display | 0.00000-00000.0 | 00000.0 | Displays to one decimal place | 00000.0 | Displays to one decimal place. |
| P5 | Display cycle | $\begin{array}{\|c\|} \hline 0.2 / 0.5 / 1.0 / 2.0 / \\ 5.0 / 10 / 15 / 30 / 60 \mathrm{sec} . \\ \hline \end{array}$ | _1.0_ | 1 sec . | 1 sec . | Measure using the default setting value as no special instruction is provided. |
| P6 | Auto zero time | $0.1-150 \mathrm{sec}$. | 006.0 | 6 sec . | 6 sec . | Measure using the default setting value as no special instruction is provided. |
| P7 | Input filter | $10 / 30 / 100 / 0.02 \mathrm{kHz}$ | 10 | 10 kHz | 10 kHz | Measure using the default setting value as no special instruction is provided. |

* For the description about the parameter functions, refer to page 20.
- Mode 4 (flowmeter mode) Display value calculation equation

| Mode 4 Display value calculation |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: |
| External input pulse (Hz) |  |  |  | A |
| Parameter setting | P1 | Number of blades per revolution |  |  |
|  | P2 | Capacity per sensor blade |  |  |
|  | P3 | Scaling |  |  |
|  | P4 | Decimal point display |  |  |
| Equation | (A * B) $*$ C $*$ D | E |  |  |

## © About scaling (parameter 3)

Assuming the flow per second to be represented in the parameter 2 flow unit (cc in the example) is $a$ (cc/s), parameter 3 will be coefficient value when a multiplier is used to change the unit of $a(\mathrm{cc} / \mathrm{s})$ for display.
(1) To display the value as in the original unit (cc/s)
$a(\mathrm{cc} / \mathrm{s}) * \underset{\downarrow}{\underset{\downarrow}{1}}=a(\mathrm{cc} / \mathrm{s})$
Parameter 3
(2) To display the value in the unit ( $\ell / \mathrm{min}$ ) as in the above setting
$a(\mathrm{cc} / \mathrm{s}) * 60 \div 1000=\mathcal{A}(\ell / \mathrm{min})$
Parameter $3 \quad * * 60 \quad$ : Multiply it by 60 as it is the flow per minute.
$\div 1000$ : Divide the value by 1000 as parameter is set in the unit of "cc".

- Start setting according to the setting example on the previous page.

*If you enter a value outside the setting range, all the input values will blink, which indicates the setting is disabled.
When this occurs, you cannot switch to other displays until you enter a value within the setting range.
(3) Function (For the setting method, refer to pages 16 and 17.)
-Function setting item in mode 4 (flowmeter mode)

| No. | Setting item | Description | Input range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| F1 | High set point 1 value | Sets the high set point 1 value | 000000-999999 | 0 |
| F2 | Low set point 1 value | Sets the high set point 1 value | 000000-999999 | 0 |
| F3 | High set point 2 value | Sets the high set point 2 value | 000000-999999 | 0 |
| F4 | Low set point 2 value | Sets the low set point 2 value | 000000-999999 | 0 |
| F5 | Hysteresis of the high and low set point 1 values | Sets the hysteresis of the high and low set point 1 values | 0-99 | 0 |
| F6 | Judgment output timer at startup | Sets the time when the comparator judgment is output at startup | 0-99 sec. | 0 sec . |
| F7 | Minimum flow(display value) | Sets the revolution speed to be displayed as zero | 000000-999999 | 0 |
| F8 | Frequency of the moving average | Used when variation of the revolution speed is large and a stable display cannot be attained | 0 (disabled)/1(3 times)/2(10 times) | 0(disabled) |
| F9 | Pre-arithmetic function | Promptly performs the deceleration display when the signal is lost | 0(disabled)/1(enabled) | 0(disabled) |

## 17. Setting Method of Functions (Excluding in the Test Mode, Common in Each Mode)

The setting method of the functions is common in each mode excluding the test mode.
For the lists of functions in each mode, refer to page 21.
-Function setting item <in mode 1 (digital tachometer mode)>

| No. | Setting item | Setting range | Default setting |  | Function description |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Display | Description |  |
| F1 | High set point 1 value* | 000000-999999 | 000000 | 0 | Sets the high set point 1 value. The decimal point is not displayed. |
| F2 | Low set point 1 value* | 000000-999999 | 000000 | 0 | Sets the low set point 1 value. The decimal point is not displayed. |
| F3 | High set point 2 value* | 000000-999999 | 000000 | 0 | Sets the high set point 2 value. The decimal point is not displayed. |
| F4 | Low set point 2 value* | 000000-999999 | 000000 | 0 | Sets the low set point 2 value. The decimal point is not displayed. |
| F5 | Hysteresis of the high and low set point 1 values | 0-99 | --- - 00 | 0 | Sets the hysteresis of the high and low set point 1 values. Used when the revolution variation is large. <br> (For details, refer to "Comparator Function" on page 17.) |
| F6 | Judgment output timer at startup | 0-99 sec. | - _ 00 | 0 sec . | Sets the time when the comparator judgment is output at startup |
| F7 | Minimum revolution speed | 000000-999999 | 000000 | 0 | Sets the revolution speed to be displayed as zero |
| F8 | Frequency of the moving average | $0($ disabled $) / 1(3$ times $) / 2(10$ times $)$ | ${ }_{-} 0_{-}$ | 0(disabled) | Used when variation of the revolution speed is large and a stable display cannot be attained |
| F9 | Pre-arithmetic function | 0(disabled)/1(enabled) | - $0_{-}$ | 0(disabled) | Promptly performs the deceleration display when the signal is lost |

*For the settings of the high set point 1 and 2 values, as well as the low set point 1 and 2 values, refer to "Comparator Function" on page 17.

- Setting method <in mode 1 (digital tachometer mode)>

For the setting methods in other modes than mode 1 (digital tachometer mode), also refer to the description below.


Continued from previous page


* If you enter a value outside the setting range, all the input values will blink, which indicates the setting is disabled.

When you press any of the numerical input key, the numerical value before entry is displayed, and you can redo the setting.

* When the relationship among the setting values of F1 to F4 is not appropriate, "EE-4" is displayed before finishing the function setting by pressing the SET key. For details, refer to page 19.


## 18. Comparator Function

- Keys to be used for the high and low set point 1 value settings and their applications


The corresponding lamp lights up according to the judgment result.

|  | Name | Function |
| :--- | :--- | :--- |
| (1) | LL lamp | Lights up when the low set point 2 is judged. |
| (2) | L lamp | Lights up when the low set point 1 is judged. |
| (3) | H lamp | Lights up when the high set point 1 is judged. |
| (4) | HH lamp | Lights up when the high set point 2 is judged. |

-Description

| - Judgment conditions |  |
| :--- | :---: |
| Low set point 1 value $\leqq$ Measurement value $\leqq$ High set point 1 value AND Low set <br> point 2 value $\leqq$ Measurement value $\leqq$ High set point 2 value | GO judgment |
| When either the high and low set point 1 value judgment or the high and low set <br> point 2 value judgment is invalid, and the other is within the setting range |  |
| Measurement value $>$ High set point 2 value | HH judgment |
| Measurement value $>$ High set point 1 value | H judgment |
| Measurement value $<$ Low set point 2 value | LL judgment |
| Measurement value $<$ Low set point 1 value | L judgment |

- Set the high set point 1, low set point 1, high set point 2, and low set point 2 values using the function items F01 to F04.
- Execute the judgment in the all measurement mode.
- The high and low set point 2 value judgment, as well as the high and low set point 1 value judgment, is executed independently.
- When both the high set point 2 and low set point 2 values are " 0 ", the high and low set point 2 value judgment is not executed.
- When both the high set point 1 and low set point 1 values are " 0 ", the high and low set point 1 value judgment is not executed.
- When both the high set point 2 and low set point 2 values, as well as the high set point 1 and low set point 1 values are " 0 ", no judgment is executed.


## - About hysteresis

When hysteresis is set in function F5, provide hysteresis between the judgment ON and OFF.
The hysteresis setting value is common to the high set point 1 , low set point 1 , high set point 2 , and low set point 2 value judgment.


- Conditions under the high set point 1 and 2 value judgment

| Judgment OFF $\rightarrow$ ON | Measurement value $>$ Judgment value |
| :--- | :--- |

Judgment ON $\rightarrow$ OFF $\quad$ Measurement value $\leqq$ Judgment value - Hysteresis value

- Conditions under the low set point 1 and 2 value judgment

Judgment OFF $\rightarrow$ ON Measurement value < Judgment value

| Judgment ON $\rightarrow$ OFF | Measurement value $\leqq$ Judgment value + Hysteresis value |
| :--- | :--- |

## 19. Memory Function

- Key to be used for the memory function and display

- During measurement, the maximum display value (MAX value) and minimum display value (MIN value) per display update cycle is always maintained.
- Pressing the MEM key allows you to check the maximum and minimum values maintained during the measurement.

- Press and hold the MEM key for 5 seconds during the normal measurement and memory display $\rightarrow$ Clears the maintained MAX and MIN values.

- As in the figure below, the maintained values are cleared when the measurement is reset (when the mode and setting value are changed, and the power is turned ON).


20. Test Mode (Function to Check if the Unit is Operating Normally)


## 21. Error Display

When an error occurs during operation, the following error codes are displayed. Take appropriate countermeasures based on the displayed code.

|  | Display | Description | Countermeasure |
| :---: | :---: | :---: | :---: |
| 1 | $\begin{aligned} & - \\ & - \end{aligned}--\quad-\quad-\quad-$ | Mode 1, 4: Displayed when the display is overflowed (the display value exceeds the available number of display digits). Mode 2, 3: Displayed when the auto zero function is executed, or the input is less than the minimum revolution speed. | When the input signal becomes within the measurement range (available number of display digits), the measurement value is displayed. |
| 2 | $E E-1$ | Displayed when the input pulse width is 10 ms or less in mode 3 (time wide meter mode). | Change the input pulse width to within the measurement range. |
| 3 | $E E-2$ | Displayed when the value is outside the teaching function range (when the input revolution speed is 99,999 or more). *For details, refer to page 7 (detailed teaching function). | Decrease the input revolution speed and execute the teaching function. |
| 4 | $E E-3$ | Displayed when an internal memory error occurs. | Press the ENT (MODE) key to release the error. Note that the setting values of modes, parameters, and functions are initialized. |
| 5 | $E E-4$ | Displayed when the setting value F01 is less than F02, or F03 is less than F04 in the function setting mode. | After the error code is displayed for 2 seconds, the display returns to the previous status before EE-4 is displayed. Change the settings. |

## 22. Parameter List

The following parameters can be set in each mode.
Parameters in mode 1 (Digital Tachometer Mode)

| No. | Setting item | Description | Input range | Default value |
| :---: | :--- | :--- | :--- | :---: |
| P1 | Pulse count per revolution | Enter the pulse count per revolution for the rotary encoder, etc. | $1-9999 \mathrm{P} / \mathrm{r}$ | $1 \mathrm{P} / \mathrm{r}$ |
| P2 | Setting revolution speed <br> (detection section) | Revolution speed in the detection section | $1-99999 \mathrm{rpm}$ | 1000 rpm |
| P3 | Value to be displayed <br> (with decimal point) | Actual value to be displayed on the panel in the above <br> revolution speed | $0.00001-999999 \mathrm{rpm}$ | 1000 rpm |
| P4 | Display cycle | Sets the display update cycle | $0.2 / 0.5 / 1.0 / 2.0 / 5.0 / 10 / 15 / 30 / 60$ sec. | 1.0 |
| P5 | Auto zero time ${ }^{* 11}$ | Sets the time from when the input pulse is gone to when the <br> display becomes "0". | $0.1-150$ sec. | 6.0 sec. |
| P6 | Input filter ${ }^{* 2}$ | Selects a minimum frequency that is larger than the maximum <br> frequency of the input signal. 0.02 kHz for the contact input | $10 / 30 / 100 / 0.02 \mathrm{kHz}$ | 10 kHz |

Parameters in mode 2 (Elapsed Timecounter Mode)

| No. | Setting item | Description | Input range | Default value |
| :---: | :---: | :---: | :---: | :---: |
| P1 | Pulse count per revolution | Enter the pulse count per revolution for the rotary encoder, etc. | 1-9999 P/r | $1 \mathrm{P} / \mathrm{r}$ |
| P2 | Setting revolution speed (detection section) | Revolution speed in the detection section | 1-99999rpm | 1000rpm |
| P3 | Value to be displayed (Hour:Minute:Second display system) | Actual value to be displayed on the panel in the above revolution speed | 0:00:01-9:59:59 | $\begin{gathered} \text { 10:00 } \\ \text { (second display } \\ \text { system) } \end{gathered}$ |
|  | Value to be displayed (second display system) |  | 0:01-999:99 |  |
| P4 | Display cycle | Sets the display update cycle | 0.2/0.5/1.0/2.0/5.0/10/15/30/60 sec. | 1 sec . |
| P5 | Auto zero time ${ }^{* 1}$ | Sets the time from when the input pulse is gone to when the display becomes " 0 ". | 0.1-150 sec. | 6 sec . |
| P6 | Input filter ${ }^{*}$ | Selects a minimum frequency that is larger than the maximum frequency of the input signal. 0.02 kHz for the contact input | 10/30/100/0.02kHz | 10 kHz |

Parameters in mode 3 (Time width meter Mode)

| No. | Setting item | Description | Input range | Default value |
| :---: | :--- | :--- | :--- | :---: |
| P1 | Hour/minute/second and $1 / 100$ <br> second display systems | Selects the time display method. | $0: 00: 00($ hour:minute:second display system) <br> $/ 0: 00(1 / 100$ second display system $)$ | $1 / 100$ <br> second display <br> system |
| P2 | Measurement section | Selects the measurement time, i.e. during input signal ON or OFF. | $0($ when OFF)/1(when ON) | 1 (ON) |
| P3 | Auto zero time ${ }^{* 1}$ | Sets the time from when the input pulse is gone to when the <br> display becomes "0". | $0.1-3600$ sec. | 3600 sec. |
| P4 | Input filter ${ }^{* 2}$ | Selects a minimum frequency that is larger than the maximum <br> frequency of the input signal. | $10 / 0.02 \mathrm{kHz}$ | 10 kHz |

Parameters in mode 4 (Flowmeter Mode)

| No. | Setting item | Description | Input range | Default value |
| :---: | :--- | :--- | :--- | :---: |
| P1 | Number of blades per <br> revolution | Sets the number of blades per revolution | $1-99(1$ when the number is unknown) | 1 |
| P2 | Capacity per sensor blade <br> (cc, $\ell$ etc.) | Enter the capacity per blade that the sensor can read. | $0.0001-99999$ | 1.0 |
| P3 | Scaling | Unit coefficient value | $0.00000-999999$ | 1 |
| P4 | Decimal point display | Designates the decimal point position | $0.00000-00000.0$ | 00000.0 |
| P5 | Display cycle | Sets the display update cycle | $0.2 / 0.5 / 1.0 / 2.0 / 5.0 / 10 / 15 / 30 / 60$ sec. | 1 sec. |
| P6 | Auto zero time ${ }^{* 1}$ | Sets the time from when the input pulse is gone to when the <br> display becomes "0". | $0.1-150$ sec. | 6 sec. |
| P7 | Input filter ${ }^{* 2}$ | Selects a minimum frequency that is larger than the maximum <br> frequency of the input signal. <br> 0.02 kHz for the contact input | $10 / 30 / 100 / 0.02 \mathrm{kHz}$ | 10 kHz |

## *1 About the auto zero time

When the input pulse becomes 0 Hz during the measurement, and the auto zero time is elapsed, the display is reset to zero.


## *2 Input filter

Set the input filter with the larger value than the input signal frequency.
Example) When the 15 kHz signal is input, set the 30 kHz filter.
Note) When the duty of the input signal (proportion of the ON time in one cycle) is low, the signal may be attenuated and the pulse may not be received normally even if you set the filter with a larger value than the input frequency. When this occurs, set the filter with an even larger value.

## 23. Function List

The following functions can be set in each mode.
Function in mode 1 (Digital Tachometer Mode)

| No. | Setting item | Description | Input range | Default value |
| :---: | :---: | :---: | :---: | :---: |
| F1 | High set point 1 value ${ }^{* 1}$ | Sets the high set point 1 value | 000000-999999 | 0 |
| F2 | Low set point 1 value ${ }^{* 1}$ | Sets the low set point 1 value | 000000-999999 | 0 |
| F3 | High set point 2 value ${ }^{* 1}$ | Sets the high set point 2 value | 000000-999999 | 0 |
| F4 | Low set point 2 value ${ }^{* 1}$ | Sets the low set point 2 value | 000000-999999 | 0 |
| F5 | Hysteresis of the high and low set point 1 values ${ }^{* 1}$ | Sets the hysteresis of the high and low set point 1 values | 0-99 | 0 |
| F6 | Judgment output timer at startup ${ }^{* 2}$ | Sets the time when the comparator judgment is output at startup | 0-99 sec. | 0 sec . |
| F7 | Minimum revolution speed | Sets the revolution speed to be displayed as zero | 000000-999999 | 0 |
| F8 | Frequency of the moving average | Used when variation of the revolution speed is large and a stable display cannot be attained | 0(disabled)/1(3 times)/2(10 times) | 0(disabled) |
| F9 | Pre-arithmetic function | Promptly performs the deceleration display when the signal is lost | 0(disabled)/1(enabled) | 0(disabled) |

Function setting item in mode 2 (Elapsed Timecounter Mode)

| No. | Setting item | Description | Input range | Default value |
| :---: | :---: | :---: | :---: | :---: |
| F1 | High set point 1 value ${ }^{* 1}$ | Sets the high set point 1 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system 0:00 |
|  |  | Sets the high set point 1 value (Second display system) | 0:00-999:99 |  |
| F2 | Low set point 1 value ${ }^{* 1}$ | Sets the low set point 1 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system 0:00 |
|  |  | Sets the low set point 1 value (Second display system) | 0:00-999:99 |  |
| F3 | High set point 2 value ${ }^{* 1}$ | Sets the high set point 2 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system0:00 |
|  |  | Sets the high set point 2 value (Second display system) | 0:00-999:99 |  |
| F4 | Low set point 2 value ${ }^{* 1}$ | Sets the low set point 2 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system 0:00 |
|  |  | Sets the low set point 2 value (Second display system) | 0:00-999:99 |  |
| F5 | Hysteresis of the high and low set point 1 values ${ }^{* 1}$ | Sets the hysteresis of the high and low set point 1 values | 0-99 | 0 |
| F6 | Judgment output timer at startup ${ }^{* 2}$ | Sets the time when the comparator judgment is output at startup | 0-99 sec. | 0 sec . |
| F7 | Minimum revolution speed | Sets the revolution speed to be displayed as zero | 000000-999999 | 0 |
| F8 | Frequency of the moving average | Used when variation of the revolution speed is large and a stable display cannot be attained | 0(disabled)/1(3 times)/2(10 times) | 0(disabled) |
| F9 | Pre-arithmetic function | Promptly performs the deceleration display when the signal is lost | 0(disabled)/1(enabled) | 0(disabled) |

Function setting item in mode 3 (Time width meter Mode)

| No. | Setting item | Description | Input range | Default value |
| :---: | :---: | :---: | :---: | :---: |
| F1 | High set point 1 value ${ }^{*}$ | Sets the high set point 1 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system$0: 00$ |
|  |  | Sets the high set point 1 value (Second display system) | 0:00-999:99 |  |
| F2 | Low set point 1 value ${ }^{* 1}$ | Sets the low set point 1 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system$0: 00$ |
|  |  | Sets the low set point 1 value (Second display system) | 0:00-999:99 |  |
| F3 | High set point 2 value ${ }^{* 1}$ | Sets the high set point 2 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system$0: 00$ |
|  |  | Sets the high set point 2 value (Second display system) | 0:00-999:99 |  |
| F4 | Low set point 2 value ${ }^{* 1}$ | Sets the low set point 2 value (Hour:Minute:Second display system) | 0:00:00-9:59:59 | Second display system$0: 00$ |
|  |  | Sets the low set point 2 value (Second display system) | 0:00-999:99 |  |
| F5 | Hysteresis of the high and low set point 1 values ${ }^{* 1}$ | Sets the hysteresis of the high and low set point 1 values | 0-99 | 0 |
| F6 | Judgment output timer at startup ${ }^{* 2}$ | Sets the time when the comparator judgment is output at startup | 0-99 sec. | 0 sec . |

Function in mode 4 (Flowmeter Mode)

| No. | Setting item | Description | Input range | Default value |
| :---: | :---: | :---: | :---: | :---: |
| F1 | High set point 1 value ${ }^{*_{1}}$ | Sets the high set point 1 value | 000000-999999 | 0 |
| F2 | Low set point 1 value ${ }^{*_{1}}$ | Sets the low set point 1 value | 000000-999999 | 0 |
| F3 | High set point 2 value ${ }^{* 1}$ | Sets the high set point 2 value | 000000-999999 | 0 |
| F4 | Low set point 2 value ${ }^{* 1}$ | Sets the low set point 2 value | 000000-999999 | 0 |
| F5 | Hysteresis of the high and low set point 1 values ${ }^{* 1}$ | Sets the hysteresis of the high and low set point 1 values | 0-99 | 0 |
| F6 | Judgment output timer at startup ${ }^{* 2}$ | Sets the time when the comparator judgment is output at startup | 0-99 sec. | 0 sec . |
| F7 | Minimum flow (display value) | Sets the revolution speed to be displayed as zero | 000000-999999 | 0 |
| F8 | Frequency of the moving average | Used when variation of the revolution speed is large and a stable display cannot be attained | 0 (disabled)/1(3 times)/2(10 times) | 0(disabled) |
| F9 | Pre-arithmetic function | Promptly performs the deceleration display when the signal is lost | 0(disabled)/1(enabled) | 0(disabled) |

*1 For details about the high set point 1 and 2 values, as well as the low set point 1 and 2 values, refer to "Comparator Function" on page 17.

## *2 About the judgment output timer at startup

When you set the value larger than 1 in the function item "F6 Judgment output timer at startup", the judgment output timer function can be used. After the power is turned on, judgment starts when the judgment output timer setting time has elapsed after the start of measurement.


## *3 About the minimum revolution speed (minimum flow)

When you set a value larger than 1 in the function item "F7 Minimum revolution speed (minimum flow)", the following functions can be used.

- In mode 1 and mode 2 , the display value is " 0 " when the measurement revolution speed becomes less than the minimum revolution speed(In mode 2 , the display shows " $",-\cdots \cdots$. $-\ldots$ ").
- In mode 4 , the display value is " 0 " when the measurement display value becomes less than the minimum flow.

Mode 1: Judgment condition: (Input frequency/P1 setting value) $* 60<$ Minimum revolution speed $\rightarrow$ Display value $=$ " 0 "
Mode 2: Judgment condition: (Input frequency/P1 setting value) $* 60<$ Minimum revolution speed $\rightarrow$ Display value $=" \because . \because . \because .-\because$ "
Mode 3: No judgment
Mode 4: Judgment condition: Display value $<$ Minimum flow $\rightarrow$ Display value $=$ " 0 "


## *4 About the frequency of the moving average

When you select values other than " 0 " in the function item "F8 Frequency of moving average", the frequency of the moving average function can be used.
Displays the measurement value per display cycle averaged by the frequency of the moving average.

- When the moving average function is not set (F8 setting value " 0 ")

- When the moving average function is set (F8 setting value " 1 ", " 2 ")

Displays the measurement value per display cycle averaged by the frequency of the moving average.
The figure below shows the relationship between the display update in the F8 setting "0" (moving average: 3 times) and averaging.


## *5 About the pre-arithmetic function

When you select " 1 " in the function item "F9 Pre-arithmetic function", the pre-arithmetic function can be used. Promptly performs the deceleration display when the input signal is lost.


When the auto zero function is activated, the display becomes " 0 " ("-. $\because .-\cdots$ " in mode 2 and mode 3 ).

## 24. Option -FVT/-FVC

When equipped with -FVT/-FVC option, analog signal output (voltage/current) is available according to the displayed data.

## 1. Specifications for -FVT/-FVC Option

| Model | -FVT/-FVC |  |  |
| :---: | :---: | :---: | :---: |
| Output | Current output | $4 \sim 20 \mathrm{~mA}$ | Select one of these four output options |
|  | Voltage output | $0 \sim 10 \mathrm{~V}$ |  |
|  |  | $1 \sim 5 \mathrm{~V}$ |  |
|  |  | $0 \sim 1 \mathrm{~V}$ |  |
| Load | Output current | below $500 \Omega$ |  |
|  | Output voltage | above $1 \mathrm{k} \Omega$ |  |
| Connector (FVC)* | Attachment: [Plug] PCS-E36SF, [Cover] PCS-E36LA (Both manufactured by HONDA TSUSHIN KOGYO CO., LTD.) |  |  |

*Cables are to be connected by the user.

## 2. Connection for -FVT/-FVC Option

## -FVT Option (Terminal block)


*Select one out of these output options
-FVC Option (Connector)

| Code | Pin number |  | Code |
| :---: | :---: | :---: | :---: |
| $4 \sim \stackrel{C+}{20 \mathrm{~mA}+}$ | 1 | 19 | $\begin{aligned} & C- \\ 4 \sim & 20 \mathrm{~mA} \end{aligned}$ |
|  | 2 | 20 |  |
| NC | 3 | 21 | NC |
| NC | 4 | 22 | NC |
| NC | 5 | 23 | NC |
| NC | 6 | 24 | NC |
| NC | 7 | 25 | NC |
| NC | 8 | 26 | NC |
| $\begin{gathered} \mathrm{V} 10+ \\ 0 \sim 10 \mathrm{~V}+ \end{gathered}$ | 9 | 27 | $\begin{gathered} \mathrm{V} 10^{-} \\ 0 \sim 10 \mathrm{~V} \end{gathered}$ |
|  | 10 | 28 |  |
| NC | 11 | 29 | NC |
| NC | 12 | 30 | NC |
| $\begin{gathered} \mathrm{V} 5+ \\ 1 \sim 5 \mathrm{~V}+ \end{gathered}$ | 13 | 31 | $\begin{gathered} \mathrm{V} 5^{-} \\ 1 \sim 5 \mathrm{~V}- \end{gathered}$ |
|  | 14 | 32 |  |
| NC | 15 | 33 | NC |
| NC | 16 | 34 | NC |
| $\begin{gathered} \mathrm{V} 1+ \\ 0 \sim 1 \mathrm{~V}+ \end{gathered}$ | 17 | 35 | $\begin{gathered} \mathrm{V} 1- \\ \sim 1 \mathrm{~V} \end{gathered}$ |
|  | 18 | 36 |  |

*Select one out of these output options
*1 and 2 are interconnected to each other. 9-10, 13-14, 17-18, 19-20, $27-28,31-32,35-36$ are also interconnected respectively.

Connector numbering
(as the plug is viewed from wire connection side)


The connector next to "1"marking is \#2 terminal.
Suggested wiring order is $1,3,5 \sim 20, ~ 22, ~ 24 \sim$ for the
ease of finding the right numbering.
Please use extra caution in soldering, as the clearance is small.

## 3．－FVT／－FVC Option Setting

When equipped with－FVT／－FVC option，following setting options are enabled from function setting feature．

| No． | Setting item | Description |  | Input | t range | Default |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| F11 | Maximum analog signal displayed value | Set the displayed value which corresponds to the maximum value of each analog signal． <br> $\cdot 4 \sim 20 \mathrm{~mA}$ ：Maximum value 20 mA <br> $\cdot 0 \sim 10 \mathrm{~V}$ ：Maximum value 10 V <br> $\cdot 1 \sim 5 \mathrm{~V}$ ：Maximum value 5 V <br> $\cdot 0 \sim 1 \mathrm{~V} \quad:$ Maximum value 1 V | Mode 1 | 「000000」～「999999」 |  | 1000 |
|  |  |  | Mode 2 | Hour：Minute：Second | 「＿0：00：00」～「＿9：59：59」 | Displayed in Seconds10:00 |
|  |  |  |  | Displayed in Seconds | 「＿000：00」～「＿999：99」 |  |
|  |  |  | Mode 3 | Hour：Minute：Second | 「＿0：00：00」～「＿0：59：59］ | Displayed in Seconds 10：00 |
|  |  |  |  | Displayed in Seconds | 「＿000：00」～「＿999：99」 |  |
|  |  |  | Mode 4 | 「000000」～「999999」 |  | 1000 |
| F12 | Minimum analog signal displayed value | Set the displayed value which forces the output of the minimum value of each analog signal． | Mode 1 | 「000000」～「999999」 |  | 1000 |
|  |  | － $4 \sim 20 \mathrm{~mA}$ ：Minimum value 4 mA <br> $\cdot 0 \sim 10 \mathrm{~V}$ ：Minimum value 0 V <br> $\cdot 1 \sim 5 \mathrm{~V}$ ：Minimum value 1 V <br> $\cdot 0 \sim 1 \mathrm{~V} \quad:$ Minimum value 0 V | Mode 2 | Hour：Minute：Second | 「＿0：00：00」～「＿9：59：59］ | Displayed in Seconds |
|  |  |  |  | Displayed in Seconds | 「＿000：00」～「＿999：99」 | 10：00 |
|  |  |  | Mode 3 | Hour：Minute：Second | 「＿0：00：00」～「＿0：59：59」 | Displayed in Seconds10:00 |
|  |  |  |  | Displayed in Seconds | 「＿000：00」～「＿999：99」 |  |
|  |  |  | Mode 4 | 「000000」～「999999」 |  | 1000 |
| F13 | Analog signal output timing | Maximum speed when the period is zero．（10ms）． When the period is 1 ，analog signal output is renewed at each display renewal cycle． ※ when the frequency is above 200 Hz | $\left\lvert\, \begin{aligned} & \left.\Gamma \quad 0 \_\right\rfloor(\text {Maximum speed }) / \\ & \Gamma \\ & \Gamma \\ & 1_{-} \end{aligned}\right. \text {(In sync with display renewal) }$ |  |  | （Maximum speed） |
|  | Analog signal output offset | Set the output offset value as the percentage of the output range for each analog signal． | 「＿－100．0］～「＿＿100．0」\％ |  |  | 0\％ |
| F14 |  | － $4 \sim 20 \mathrm{~mA}$ ：Output range 16 mA <br> $\cdot 0 \sim 10 \mathrm{~V}$ ：Output range 10 V <br> $\cdot 1 \sim 5 \mathrm{~V}$ ：Output range 4 V <br> $\cdot 0 \sim 1 \mathrm{~V}$ ：Output range 1 V |  |  |  |  |

When offset is OFF（off set F14＝0）


When offset is ON（off set F14＞0）

| Condition | Analog output value |
| :--- | :--- |
| displayed value $\geqq$ F11 | Maximum value（20mA，10V，5V，1V） |
| F12 $<$ displayed value $<{\mathrm{F} 11^{\prime}}^{\prime} *$ | （Maximum value／F11）$\times$ Measured value for analog output＋ <br> （Offset value） |
| displayed value $\leqq \mathrm{F} 12$ set value | Minimum value（4mA，0V，1V，0V）＋（Offset value） |

※ F11＇is the displayed value when the analog output value，including F14（\％）of the output range，is equal to the MAX value．
Example）Assuming the output is $10 \mathrm{~V}, \mathrm{~F} 11=200, \mathrm{~F} 14=10(\%)$ ，then $\mathrm{F} 11^{\prime}=180$ ，
therefore the output is 10 V when the displayed value is above 180 ．

When offset is ON（off set F14＜0）


| Condition | Analog output value |
| :--- | :--- |
| displayed value $\geqq$ F11 | Maximum value（20mA，10V，5V，1V） |
| F12 $<$ displayed value $<{\mathrm{F} 11^{\prime}}^{\prime} *$ | （Maximum value／F11）$\times$ Measured value for analog output－ <br> （Offset value） |
| displayed value $\leqq \mathrm{F} 12$ set value | Minimum value（4mA，0V，1V，0V）－（Offset value） |

※ The minimum value for MIN－F14（\％）in the diagram above is 0 mA ，in the case of current output（ $4 \sim 20 \mathrm{~mA}$ ）
Example）Assuming the output is $10 \mathrm{~V}, \mathrm{~F} 11=200, \mathrm{~F} 14=-10(\%)$ ，then $\mathrm{F} 11^{\prime}=220$ ，
therefore the output is 10 V when the displayed value is above 220 ．

## 25. Option -BCD

When equipped with -BCD option, Binary Coded Decimal output is possible

## 1. Specifications for -BCD Option

| Model | -BCD |
| :---: | :---: |
| NPN Open collector output | Output capacity 3 30VDC 20 mA |
| Open collector input | Open collector (NPN) input |
|  | LO input $\quad$ Load capacity : minimum 5mA |
|  | LO input $0 \sim 1.5 \mathrm{~V}$ |
|  | HI input Leakage current : maximum 0.1mA |
| Data output | 6 digits BCD code |
| Decimal point output | DP1 $\sim 4$ ( $1 \sim 4$ digits after decimal point) |
| Control output | PLUS $\quad$ When output data is positive, PLUS turns to LO |
|  | DT OUT $\quad$ When DATA OUT is HI, output signal is set |
|  | OVR $\quad$ When displayed value overflows, OVR turns to LO |
| Control input | HOLD $\quad$ While HOLD is LO, output data does not renew |
|  | ENABLE While ENABLE is LO, output has high impedance |
| Connector | Meter :PCS-E36LMD/ Accessory side: [Plug] PCS-E36FS, [Cover] PCS-E36LA (Both manufactured by HONDA TSUSHIN KOGYO CO., LTD.) |

Positive-logic-negative-logic available for BCD and decimal point output (opted at Function 10)
※ Cable connection is to be done by users.

- Timing chart



## 2. Connection for -BCD Option

| in/out | Code | Pin number |  | Code |  | in/out |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Out put | $\times 10^{0}$ | 1 | 19 | 1 | $\times 10^{3}$ | Out put |
|  |  | 2 | 20 | 2 |  |  |
|  |  | 3 | 21 | 4 |  |  |
|  |  | 4 | 22 | 8 |  |  |
|  | $\times 10^{1}$ | 5 | 23 | 1 | $\times 10^{4}$ |  |
|  |  | 6 | 24 | 2 |  |  |
|  |  | 7 | 25 | 4 |  |  |
|  |  | 8 | 26 | 8 |  |  |
|  | $\times 10^{2}$ | 9 | 27 | 1 | $\times 10^{5}$ |  |
|  |  | 10 | 28 | 2 |  |  |
|  |  | 11 | 29 | 4 |  |  |
|  |  | 12 | 30 | 8 |  |  |
|  | PLUS | 13 | 31 |  | DP1 |  |
|  | DT OUT | 14 | 32 |  | DP2 |  |
|  | OVR | 15 | 33 |  | DP3 |  |
| Input | HOLD | 16 | 34 |  | DP4 |  |
|  | ENABLE | 17 | 35 |  | GND |  |
|  | GND | 18 | 36 |  | GND |  |

Connector numbering
(as the plug is viewed from wire connection side)


The connector next to " 1 "marking is \#2 terminal.

- Suggested wiring order is 1, 3, $5 \sim 20, ~ 22, ~ 24 \sim$ for the ease of finding the right numbering. - Please use extra caution in soldering, as the clearance is small.

HOLD input circuit


Output circuit


ENABLE input circuit


## 3. -BCD Option Setting

When equipped with -BCD option, following setting options are enabled from function setting feature.

| No. | Setting item | Description | Input range | Default |
| :---: | :---: | :---: | :---: | :---: |
| F10 | BCD output logic | Set as 0 for negative logic, set as 1 for positive logic <br> (decimal point output) | $\left.\Gamma_{-} 0_{-}\right\rfloor($Negative logic)/ <br> $\left.\Gamma_{-} 1_{-}\right\rfloor($Positive logic) | Negative logic |

※ F10 sets positive/negative logic for BCD output, Decimal point output, PLUS, OVR.
Logic for DT OUT, HOLD, ENABLE signals cannot be set.

- BCD output display specifications


BCD output
$=$

## 000123

Hour:Minute:Second


Display OVR output


For Hour:Minute:Second display, ":" becomes "."


For Seconds display, ":" becomes "."


## 26. Option -TRT

When equipped with -TRT option, comparison result output is possible.(LL,L,GO,H,HH,ZERO)

## 1. -TRT option specifications

| Model | -TRT |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: |
| Output capacity | 30 VDC 20 mA | LL signal is ON |  |  |  |
| Rsidual voltage | Less than 1.5V | L signal is ON |  |  |  |
| Output signal | Measured value < Low set point 2 value | H signal is ON |  |  |  |
|  | Measured value < Low set point 1 value | HH signal is ON |  |  |  |
|  | Low set point 1 value $\leqq$ Measured value $\leqq$ High set point 1 value | GO signal in ON |  |  |  |
|  | High set point 1 value $<$ Measured value | ZERO signal is ON |  |  |  |
|  | High set point 2 value < Measured value |  |  |  |  |
|  | Measured value $=0$ |  |  |  |  |
| Output is insulated from internal circuitry |  |  |  | Negative logic open collector output |  |

## 2. -TRT option connection



## 27. Option -CPT

When equipped with -CPT option, comparison result output is possible.(L,GO,H)

## 1. -CPT option specifications

| Model |  | - CPT |  |
| :---: | :---: | :---: | :---: |
| Output contact |  | 1C |  |
| Rated load | Resistance load | 250VAC 5A 100K operations |  |
|  |  | 30VDC 5A 100K operations |  |
|  | Induction load $\cos \phi=0.4$ | 250VAC 2.5 A 100 K operations |  |
|  |  | 30 VDC 2.5 A 100 K operations |  |
| Output signal | Measured value < Low set point 1 value |  | La signal is ON |
|  | Low set point 1 value $\leqq$ Measured value $\leqq$ High set point 1 value |  | GOa signal is ON |
|  | High set point 1 value $<$ Measured value |  | Ha signal is ON |

## 2. -CPT option connection



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[^0]:    * For the description of functions, refer to pages 21 and 22.

[^1]:    * For the description of functions, refer to pages 21 and 22.

